## **Interactive Software Verification SS 2013**

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## SHEET 7 Lists and the Heap

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Goals You get a deeper knowledge of Burstall's memory model.

## Exercise 1 [4] Heap Basics

- 1. What is the meaning of p, q, and xs in the abstraction predicate list node-alloc node-next p xs q for lists?
- 2. What is the purpose of the parameters node-alloc and node-next?
- 3. For every abstraction predicate, we need a separation lemma. What is its purpose? (Look at examples and then give a general explanation)
- 4. Why can Burstall's memory model not be used for arbitrary C programs? Give an example for a program, which is not correctly modeled.

## Exercise 2 [6] Sum of List Elements

(a) [5] The following code iterates through a list at p and computes the sum of all elements

```
s = 0;
while (p != null) {
    s = s + p->data;
    p = p->next;
}
```

The precondition requires that the list is allocated and binds the auxiliary variable P.

list node-alloc node-next p XS NULL  $\land$  p = P

The postcondition ensures that the result s is really the sum of the data fields of the list elements. s = listsum (list-data node-data XS)

The invariant is similar to list\_length from the lecture, but we need to consider the part of the list we already visited, too.

∃ ys zs. list node-alloc node-next P ys p ∧ list node-alloc node-next p zs NULL ∧ XS = ys @ zs ∧ s = listsum (list-data node-data ys)

Your task is to do a detailed proof to understand which lemmas are required at which point.

(b) [1] Try to find a proof which is as automatic as possible. For this, extend the current simpset step-by-step by using

declare  $\cdots$  [simp]

instead of passing the theorems to every simp call.